femto femto engineering - Best Practises SOL 401/402 - v01.2021

# **basics 401/402 solver** Where to find your information.

#### manual

See Quick Reference Guide and Multi\_Step User's Guide for more information.

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0	Help Topics	Ctrl+H	
	Toolbars	•	
	Dockable Panes	•	
	TMG Thermal and	Flow	
	Simcenter Nastran	N	
	Analysis	3	

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	Using Simcenter Nastran
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## contact property Femap help

At the Define Connection Property window in Femap, press FI to get extensive help on the connection parameters.

1	Title		Type 0Contact
C	blor 110	Layer 1	ē
	Nastran Autodesk Na		
	tep Structural (401)	Multistep Kinematic (402	
	ntact Pair (BCTSET)	-	rty (BGSET - BGPARM )
Friction	0.	Search Distance	0.
		Target Extension Fac	tor 0.
		Rotation Constraint	0Auto 🗸
Contact Property (B		7	
Initial Penetration	0Default ~	Regularization Models	0Stiffness Betweer V
GAPVAL	0.	Value	0.
PENDEPTH	0.	Normal Reg. Type	0Specify Regularizi V
OFFSET	0.	Value	1.
Segment Normal	0Auto - Using NSIE 🗸	NormDist vs Press	0None - Ignore 🗸 🗸
Tied Regions	0Not Tied - Default 🗸	O Normal Modulus 0.	
Tied Tolerance	0.	Compliance Factor	0.
Surf Extension Factor	0.	Friction Model	0Constant Friction $ \smallsetminus $
Large Displacemer	t Contact Formulation	Friction Param 1	0.
Double Sided Cont	act	Friction Param 2	0.
Contact Active at	Beginning of Analysis	Critical Sliding Velocity	0.
Include Shell Thick	ness Offset	Transition Time	0.
Normal Vel Coeff.	0None - Ignore V	Frict vs Slide Vel	0None - Ignore 🗸 🗸
Tangent Vel Coeff.	0None - Ignore V	Frict vs Time	0None - Ignore 🛛 🗸
rangent ver overn.	oundrie - synore - V	Frict vs Temp	0None - Ignore 🗸 🗸

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# **basics 401/402 solver** Where to find your information.

# loads

If time functions are used to define the load, at the boundary conditions the load set must be defined at Loads (Time)

If no time functions are used to define the load, parameter LVAR decides if the load should be ramped or applied at once.

Primary Sets		Contact Sets		
Constraints	1Constraint	All Connectors		
Constraint Equations	0From Constraint Set	Connection(s)	0None	~
		O None		
Loads	0None	Contact Property	0None	~
Loads( Time )	1Load	~		
Townset and (Tolt)	a Nore	Glue Sets		
Temperatures(Init)	0None	All Connectors		
Temperatures(Load)	0From Load Set	Connection(s)	0None	~
Bolt Preloads	0From Load Set	✓ ○ None		
Initial Conditions	0None	Glue Property	0None	~

Multi-Step Control Options	×
Skip NLCNTL2	
Time Stepping	Analysis Control
Automatic Time Stepping (AUTOTIM)	Maximum Displacement (DISLIM) 0.
First Time Step Size (DTINIT) 0.	Maximum Rotation (ROTLIM) 0.1
Minimum Time Step (DTMIN) 0.	Maximum Deformation (DEFLIM) 0.1
Maximum Time Step (DTMAX) 0.	Time Unassigned Loads (LVAR)
Maximum Increase Ratio (EQMFMX) 1.9	Time Assigned Temp Loads (TVAR) 0Ramp 1Step
Maximum Decrease Ratio (EQMFMIN) 2.1	Predict Displacement (DIPR)
Number of Iterations (ITEREF) 6	Force Normalization (NORM)
Negative Pivot Time Step Rejection (RJPN) 0Never ~	Unsymmetrical Matrices for Complex Modes (MATSYM)
Zero Pivot Time Step Rejection (RJPZ)	Enable Inertia in Dynamics (INERTIA)
Integration Error Control (TSDYN)	Save Data at Beginning of Computation (IAR0)
Activate Time Stepping Based on Disp/Temp Error (ERCD)	Plasticity and Creep Control
Allowable Change/Step (PRED) 0.	Enable Plasticity
Viscous Material Options	Enable Creep
Integration Error Control (TSVSC)	Creep Integration Factor (CRINFAC) 0.5
Error Threshold (VSCOTE) 0.1	Internal Restart
Min Stress Factor (VSCOSN)	Restart Computation (RSUB)
Iteration and Convergence	Prev., Next., OK Cancel

## settings

In the analysis set manager you can find the default settings. In the following slides some suggestions are made whether or not to keep the default settings.

Master Request	s and Conditions			×
Analysis Type	1Static			~
Case ID Subtitle Label Manual Control		Eigenvalu	Je	<u>}</u>
Manual Control Skip Standard Ending Text Inside Case				t Text (Off) Text (Off)
Prev	Next	OK		Cancel

In the <u>Master Requests and</u> <u>Conditions</u> the different <u>Analysis Types</u> can be chosen. femto Femto engineering - Best Practises SOL 401/402 - v01.2021

# **settings sol 402** Executive and Solution Options

## sol 601

NASTRAN Executive and Solution Options	×
Solver Direct Output To	
Base Filename for Analyze (Blank to Match Model)	
Additional Command Line Arguments	
Executive Control Problem ID Solution Override Max Time (in minutes)	MSC/MD Nastran Version  Ver 2001 Ver 2004 or later  Previous Versions  Solution Options
Diagnostics	Iterative Solver 0Off
Extended Error Messages	Number of Processors 4
Extended Solution Status Monitoring	Solver Memory (MB 0=Auto) 0 GPU Computing 0DCMP, FRRD: ~
Restart Control Save Databases for Restart Restart Previous Analysis From	ly Restart
Version Starting Sub	case
Manual Control	Start Text (Off)
Prev Ne <u>x</u> t Scratch Files	. <u>O</u> K Cancel

Number of real processors(cores) 601 only supports SMP parallelism

#### sol 402

NASTRAN Executive and Solution Options	×
Solver	
Direct Output To	
Additional Command Line Arguments	MPI402=4
Executive Control Problem ID Solution Override	MSC/MD Nastran Version <ul></ul>
Max Ime (in minutes) Diggnostics System Cells	Solution Options Iterative Solver 0Off
Extended Error Messages	Solver Memory (MB 0=Auto) GPU Computing ODCMP, FRRD.
Restart Control Saye Databases for Restart Restart Previous Analysis From Version Starting Subc	
Manual Control	Start Text (Off) End / DMAP Text (Off)

This command switches on DMP parallelism for 4 cores. For DMP > 4 an extra license is needed.

#### In Sol 401 DMPPARALLEL = 4

Mixed DMP/SMP parallelism possible: If Number of processors = 2 then 4 additional SMP cores are used: SMP\*DMP = 2 \* 4 = 8.

SMP\*DMP should not exceed the number of real processors of your machine.

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# Bulk Data Settings

# **60 I**

Portio	n of Model to Writ	but rbe3 V	
AUTOSPC	0Eigenvalue v	ALPHA1 Real 0.	Number of real processors(cores) 601 only supports SMP parallelism
GRDPNT	1.	Complex 0.	
KGROT	100.	Complex 0.	
	10000000. 0.01	Format ( ) Small Field	
BOLTFACT	-2Automatic(Static V	O Large Field (CSys, Material, Prop)	
	0Constraint Mode 🗸	Large Field (Csys, Node)     Large Eield (All But Elements)	
SWPANGLE	0.	O Large Field Translator Options	
	1 ~	All Plates as QUADR/TRIAR	
		Gaps as Contact ODefault  Dynamic Loads using LOADSET/LSEQ  Write All Static Load/BC Sets	Small displacement and small strain
	MODACC RESVEC On Off	Rigid Element Method 2LINEAR  Manual Control Skip Standard Bulk Data	formulation
SRCOMPS	CNTASET	End Text at End of File Outside Bulk Start Text (Off) End Text (Off)	Sol 402 Leaves STRMEAS and STROUT to

**402** 

NASTRAN Bulk Da	ALITOSPC         DEgenvalue            Igr.DPVT         0         Complex           UgtTMASS         1         Complex           JALPHA2         Real         0.           MAYRATD         10000000.         Format           JBREL         O         0.           BOLTFACT         10000000.         Format           BOLTFACT         10000000.         Large Field (CSys, Material, Prop)           SWPANGLE         0.         Clarge Field (CSys, Node)           SWPANGLE         0.         Clarge Field All But Elements)           OOF         1         Skip BeangBar Cross Sections           MATNL         10n         Clarge root sot sections	×		Multi-Step Global Control Options		
	on of Model to Write 5all bu			Global Parameters (SOL402)		
PARAM ALTOSPC GRDPNT WTMASS KGROT MAXRATIO NDAMP INREL	gRDPNT             0               Complex               0.                 WTMASS             1.               Lapha2             Real             0.               0.                 MgROT               100.               Complex             0.               0.                 MgRATIO               10000000.               Format               0.                 INREL               Varge Field (CSys, Material, Prop)               Large Field (Csys, Node)		ſ	Solver Type (RESO) Stress-Strain Measure for Plastic Matl. (STRMEAS) Stress-Strain Measure for Output (STROUT) Stress-Strain Conversion Method (STRCONV) Computation (IREF)	3Parallel     >       2Biot Strain, Biot     >       2Biot Strain, Biot     >       1Standard Metho     >       0No Initial Static + >	
BOLTFACT	Portion of Model to Write B.allbut rive3 Parama Portion of Model to Write B.allbut rive3 Parama Portion of Model to Write B.allbut rive3 Parama Param	Large Field (Csys, Node)     Large Field (All But Elements)     Large Field Translator Options     All Plates as QUADR/TRIAR		Advanced Parameters (SOL402) Threshold for Zero Pivots (PRECPIVO) Modes to Save as Output (NKINE)	10	
LIGDISP ( LIGDISP ( LIGSTRN ( PHIPSI OFEOM SRECOMPS NCFISR BR LOUT		0				
Prev	Negt	QK Cancel		Prev <u>Nex</u> t <u>Q</u> K	Cancel	

RESO to "Parallel" mostly is faster

Preferred to the default "exact method"

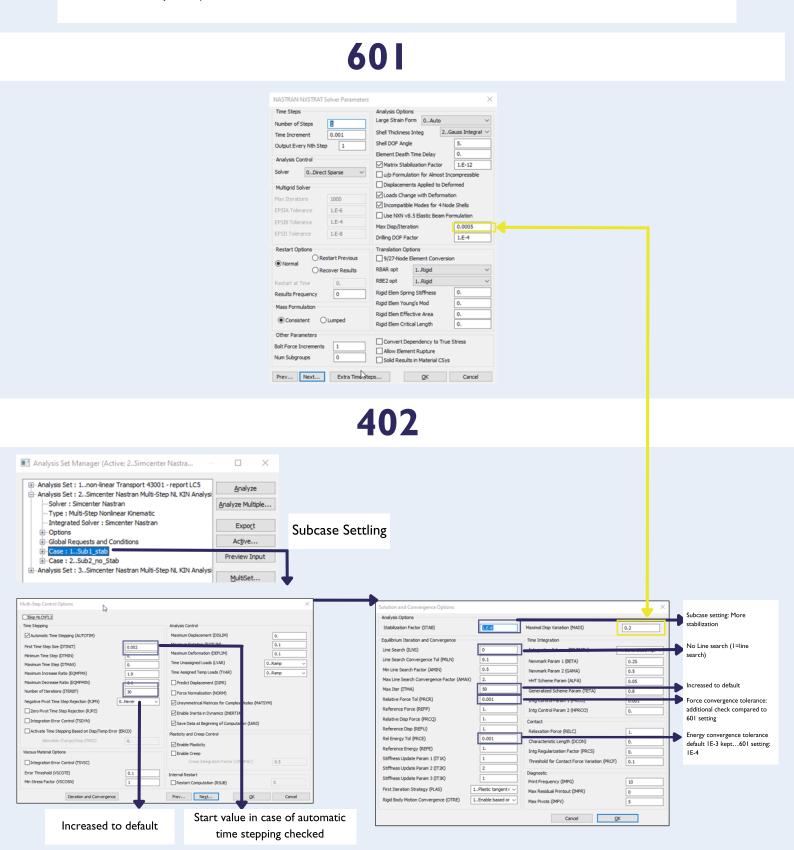
LGSTRN checked would switch on STRMEAS and STROUT to I:True values.

In contrast to 601 it is possible to use an engineering material curve, convert it internally to a TRUE curve, do a LGSTRN simulation (STRMEAS=1), and convert the results back (STRCONV) to Engineering values (STROUT=2) for direct input curve/output value comparison.

# setting Sol 402

If settings in the beginning of the analysis require different settings, e.g. due to contact settling, then subcases can be useful.

401/402: <u>Subcases</u> supported to modify solution settings in contrast to 601 (where a restart would be required)

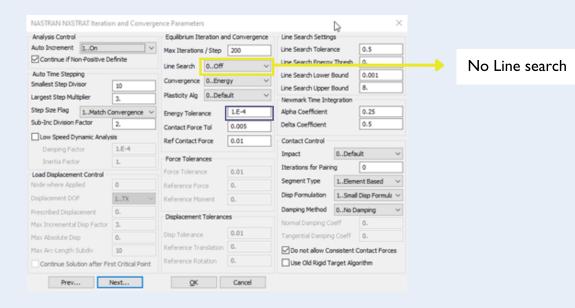


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# setting Sol 402

401/402: Subcases supported to modify solution settings in contrast to 601 (where a restart would be required)

# 60 I



# 402

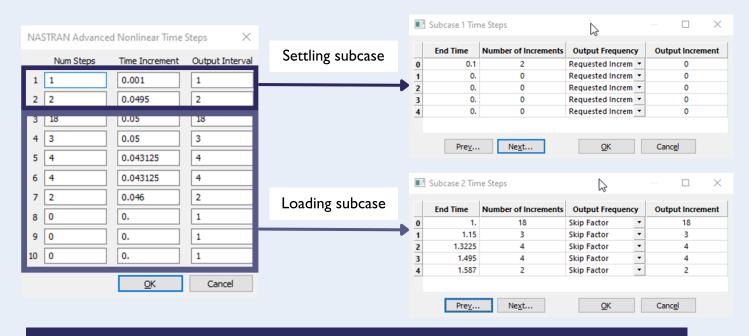
Analysis Set Manager (Active: 2Simcenter Nastra Analysis Set : 1non-linear Transport 43001 - report LCS Analysis Set : 2Simcenter Nastran Multi-Step NL KIN Analysi Solver : Simcenter Nastran Multi-Step NL KIN Analysi Analyze Multiple Ditegrated Solver : Simcenter Nastran Gobal Requests and Canditione Gobal Requests and Canditione Case : 1Sub1_stab Case : 2Simcenter Nastran Multi-Step NL KIN Analysi Analysis Set : 3Simcenter Nastran Multi-Step NL KIN Analysi Analysis Set : 3Simcenter Nastran Multi-Step NL KIN Analysi Analysis Set : 3Simcenter Nastran Multi-Step NL KIN Analysi	ase loading	
Multi-Step Control Options         X           Bite MCOTT_2         Analysis Control           Time Stepping         Analysis Control           Multi-Step Topology         Maximum Diplocement (DSLM)	Solution and Convergence Options Analysis Options Stabilization Factor (STAB) Egylithum Iteration and Convergence Time Integration	Subcase setting: no stabilization(default)
Maximus Estançare (MUTRIN)         0.           Part Time Step Step (DTRVT)         0.           Maximus Time Step (DTRVT)         0.           Immed Time Step (DTRVT)         0.           Immed Time Step (DTRVT)         0.           Integration Fare Control (TSRVT)         0.           Integration Fare Control (TSRVT)         0.           Activate Time Step (DTRVT)         0.           Activate Time Step (DTRVT)         0.           Maximus Concert (TSRSC)         0.           Integration Factor (TSRVC)         0.5           Integration Factor (TSRSC)	Decision for convergence         0         1           Line Sarch (Disc)         0         1         1         0         1         0         1         0         1         0         1         0         1         0         1         0         1         1         0         1         1         0         1         1         0         1         1         0         5         1         1         0         5         1         1         0         5         1         1         1         5         1         1         5         1         1         1         5         1	No Line search ILNS = 1, then Line Search

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# setting time steps

# 60 I

# 402



# contact settings

# 60 I

# 402

Connection Pro	operty		×	Define Connection P	roperty			
1	Title Z-shim (friction 0 or 1)	Туре	0Contact ~	ID 1	Title Z-shim (friction 0 or 1	)	Type 0Cont	tar
Co	lor 110	Layer 1	2	c	color 110	Layer 1		
	Nastran Autodesk Nast	an ranges return	-DYNA MARC Adv Nonlin (601)		C Nastran Autodesk Nas			
	tep Structural (401) ed Contact Property (BGSE		KOV INDRIIN (601)		step Structural (401) ontact Pair (BCTSET)	Glued Contact Proper		
ion Factor	0.	,		Friction	0.5	Search Distance	10.	
	0.			FICOUT	0.5	Target Extension Fac		
Type 0	Constraint Function	Standard Contact Algorithm	E. I.F.			Rotation Constraint	0Auto	
vie-Sided	Constraint Function +	Disp Formulation 1Small Disp	p Formulatio V	Contact Property (E	CTPAR2)	Procasor Conscience	0111010	_
enetration	0.,Eliminate V	Consistent Stiffness		Initial Penetration	AL for Closest Node 🗸	Regularization Models	0Stiffness Betv	we
ance	0Elminate	_	0.	GAPVAL	0Default 1Initial Penetrations - El	minated	-2.	
ion Depth	1Eliminate/Prinks* 2Ignore		0.	PENDEPTH	2. Initial Penetrations - Ig	nored	Automatic	-
Vormal	3Specify with Gap D 0Default			OFFSET	<ol> <li>Initial Penetrations - GAPVAL Override</li> <li>Izero Penetrations for Closest Node</li> </ol>		1.	-
pe	0Single Sided V	Friction Model 0Default (		Segment Normal	13Set Penetrations to G 0Auto - Using NStl	NormDist vs Press	0None - Ignore	e
tance	0.		0.5	Tied Regions	0Not Tied - Default ~	O Normal Modulus	0,	-
col rec	0.	Friction Param 2	0.	Tied Tolerance	0.	O Compliance Factor	1.E-10	,
	0.		0.	Surf Extension Facto	r 0.	Friction Model	0Constant Frict	ctic
			0.	Large Displaceme	nt Contact Formulation	Friction Param 1	0.	-
	ontact Algorithm		0.	Double Sided Con		Friction Param 2	0.	-
nstraint	0.	Friction Delay		_	t Beginning of Analysis	Critical Sliding Velocity	0.	-
Constraint	0.	Rigid Target Options		Include Shell Thid		Transition Time	0.	
e Factor	0.	roge in get open a				Frict vs Slide Vel	0None - Ignore	e
				Normal Vel Coeff.	0None - Ignore V	Frict vs Time	0None - Ignore	e
				Tangent Vel Coeff.	0None - Ignore 🗸 🗸	Frict vs Temp	0None - Ignore	

Additional option 13 specified: The contact region is shifted with the very small (unphysical) initial penetration of the closest node (See f06), such that the closest node becomes initially stress free touching. femto femto engineering - Best Practises SOL 401/402 - v01.2021

# example contact settings

# **60 I**

#### **402**

Define Connection Property	×	Define Connection Property	3
ID 2 If the X and Y shims (friction of Golor 110	)) Type 0Contact V Layer 1	D         2         Title X and Y shims (friction           Color         110	a 0) Type 0Contact v Layer 1
	Aultistep Kinematic (402) Adv Nonlin (601)	Linear Multistep Structural (401)	tran ABAQUS ANSYS LS-DYNA MARC Multistep Kinematic (402) Adv Nonlin (601)
Sincenter Nastran Glued Contact Property (BGSE Extension Factor 0.	r)	Sincenter Nastran Contact Pair (BCTSET) Friction	Gued Contact Property (BGSET - BGPARM) Search Distance 10.
General Contact Type 0Constraint Function V	Standard Contact Algorithm Disp Formulation Disp Formulation		Target Extension Factor         0.01           Rotation Constraint         0Auto         ~
Double-Sided Initial Penetration 0Eliminate	Consistent Stiffness	Contact Property (BCTPAR2)	Regularization Models 0Stiffness Betweer V
Gap Distance 0.	Init Penetration Duration 0.	GAPVAL 0.	Value -2.
Penetration Depth 0. Segment Normal 0., Default	Surface Extension Factor 0.	PENDEPTH 0. OFFSET 0.	Volue -3Automatic ~
Offset Type 0Single Sided ~	Friction Model 0Default (Param 1) ~ Friction Param 1 0.	Segment Normal 0Auto - Using NSIE ~ Tied Regions 0Not Tied - Default ~	NormDist vs Press     0None - Ignore
Offset Distance 0. Birth Time 0.	Friction Param 2 0.	Tied Tolerance 0.	Compliance Factor
Death Time 0.	Friction Param 4 0.	Surf Extension Factor 0.	Friction Model 0Constant Friction ~
Constraint Function Contact Algorithm Normal Constraint 0.	Friction Param 5 0.	Double Sided Contact	Friction Param 2 0.
Frictional Constraint 0. Compliance Factor 1.E-10	Rigid Target Options	Contact Active at Beginning of Analysis Include Shell Thickness Offset	Critical Sliding Velocity 0. Transition Time 0.
		Normal Vel Coeff. 0None - Ignore v Tangent Vel Coeff. 0None - Ignore v	Frict vs Side Vel         0None - Ignore         \vee           Frict vs Time         0None - Ignore         \vee           Frict vs Temp         0None - Ignore         \vee
Defaults Loag Save	Copy QK Cancel	Defaults Load Save	Copy QK Cancel

Connection property without friction, with compliance